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Diverse Control Techniques For The Most Part Intended For UAVs Are Feedback Linearization [2], [3], Back-stepping Control [4], And Siding Mode Control (SMC) [5], [6]. Manuscript Received November 22, 2018; Revised July 22, 2019. Some Different Techniques Are Implemented On A Linearized Model Of Quadrotor And A Comparison Of The Jun 1th, 2024

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The Passive FTC Approach Has The Drawback Of Being Reliable Only For The Class Of Faults Expected And Taken Into Account In The Design. However, It Has The Advantage Of Avoiding The Time Delay Required In Active FTC For On-line Fault

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