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Makeblock Constructor I 3D Printer Kit 19 2.4.1 Wiring Four Stepper Motors Step1. Connect The X Motor To The Connector Labeled X. Ensure The Red Cable Is Closest To The Green Screw Terminals On The RAMPS Board (Wire Orders From Left To Right: Red, Blue, Green And Black). Note: If You Don't Wiring By Color Order, The Motor Motion Will Be Incorrect. Jan 10th, 2024

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#define IMU\_SDA\_PIN 21 #define IMU\_SCL\_PIN 22 Using The IMU The IMU On The Shield Is The LSM9DS1, Which Is Connected The The ESP32 Thing To The I2C Port Only. Any Of The Examples From The LSM9DS1 Library Should Feb 10th, 2024

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Adafruit 2 Channel Relay Numato Shield.
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Adafruit NeoPixel Shield.
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Methods And Fuzzy Logic For Mobile Robot Control," Inte. Power Electronics And

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