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Contribution Leading To New Control Theory. Several Other Methods Of Robust Control, Such As Sliding Modes And Lyapunov Methods, Have Also Been Applied To The Robust Control Problem For Robot Manipulators. The Mid-1980s Were Also A Time Of Development In Adaptive Control, And Again The Connection With Robotics Was Pursued. Jun 1th, 2024

A Colony Of Robots Using Vision Sensing And Evolved Neural ...

T. C. Henderson School Of Computing University Of Utah 50 S. Central Campus Drive, Room 3190 Salt Lake City, UT 84112
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