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BRUNO SICILIANO'S CV (SUMMER 2021)

BRUNO SICILIANO [Bm-1] C. Canudas De Wit, B. SICILIANO, G. Bastin (Eds.), Theory Of Robot Control, Springer-Verlag Communications And Control Engineering Series, London, UK, 1996 Edited Volumes [Be-12] B. SICILIANO, F. Ruggiero, Robot Dynamic Manipulation: Perception Of Deformable Objects And Nonprehensile Manipulation Control, Springer Tracts In Apr 14th, 2024

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